



Parameter Free Piecewise Dynamic Time Warping for time series classification

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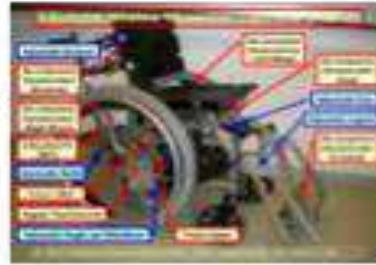
Blaise Pascal University, Clermont-Ferrand II, France

Context and motivations

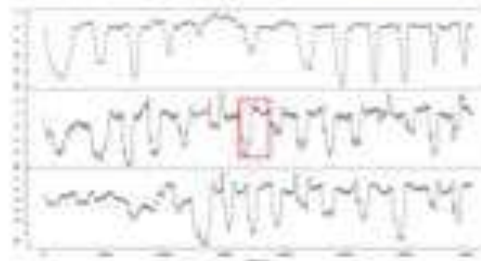
Siyou *et al.*, CML@ICML 2015

CONTEXT AND PROBLEM

– The biomechanical analysis of human being movements during their locomotion is performed with various measuring instruments (sensors)



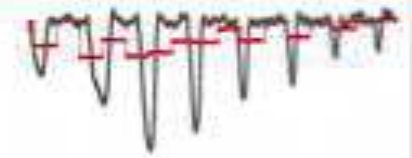
– Those measuring instruments recorded long time series composed of many cycles or patterns, representative of the movements made and effort produced by the subject during his displacement



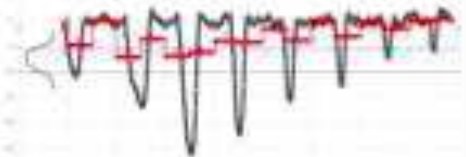
– These cycles are the time series analysis units and have several characteristic properties : minimum, maximum, duration, mean, median, standard deviation, interquartile range, the area below the cycle.



– Piecewise Aggregate Approximation



– Symbolic Aggregate Approximation



– ESAX



– SAX-TD



– Our goal is to provide a symbolic representation that takes into account several properties for each cycle, but without increasing the number of symbols used for the representation.

Outline

Background

- DTW, PDTW, IPDTW

Contribution

- FDTW

Conclusion & prospects

- Conclusion
- Future works

Time series classification

- ▶ Web site comparison
- ▶ PAA + DTW is among the good classifiers

« No free lunch theorem »



Time series

Definition

$X = x_1, \dots, x_n$ is a sequence of numerical values representing the evolution of a specific quantity during the time. x_n is the most recent value.

Definition

A segment X_i of length l of the time series X of length n ($l < n$) is a sequence constituted by l consecutive variables of X starting at the position i and ending at the position $i + l - 1$. We have:

$$X_i = x_i, x_{i+1}, \dots, x_{i+l-1}$$

Time series

Definition

The arithmetic average of the data points of a segment X_i of length l is noted \bar{X}_i and is defined by:

$$\bar{X}_i = \frac{1}{l} \sum_{j=0}^{l-1} x_{i+j}$$

PAA, PDTW

Definition

Let T be the set of time series. The Piecewise Aggregate Approximation (PAA) is defined as follows:

$$PAA: T \times \mathbb{N}^* \rightarrow T$$

$$(X, N) \mapsto PAA(X, N) = \begin{cases} \bar{X}_1, \dots, \bar{X}_N & \text{if } N < |X| \\ X & \text{otherwise} \end{cases}$$

Definition

Let $N \in \mathbb{N}^*$, X and Y be two time series.

$$PDTW(X, Y, N) = DTW(PAA(X, N), PAA(Y, N)).$$

DTW

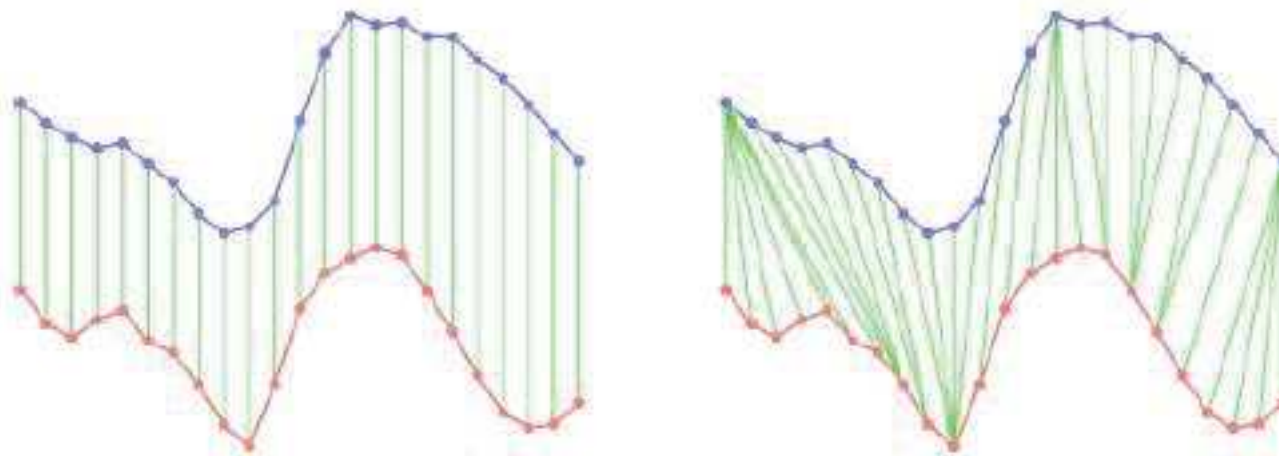
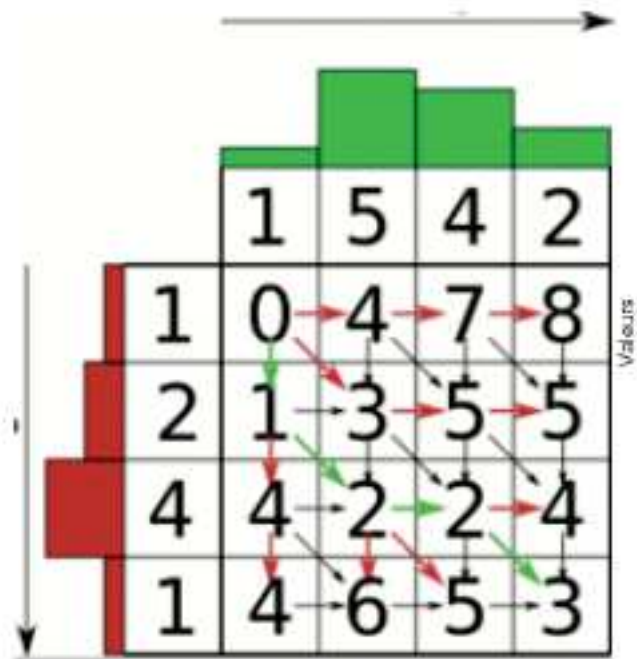


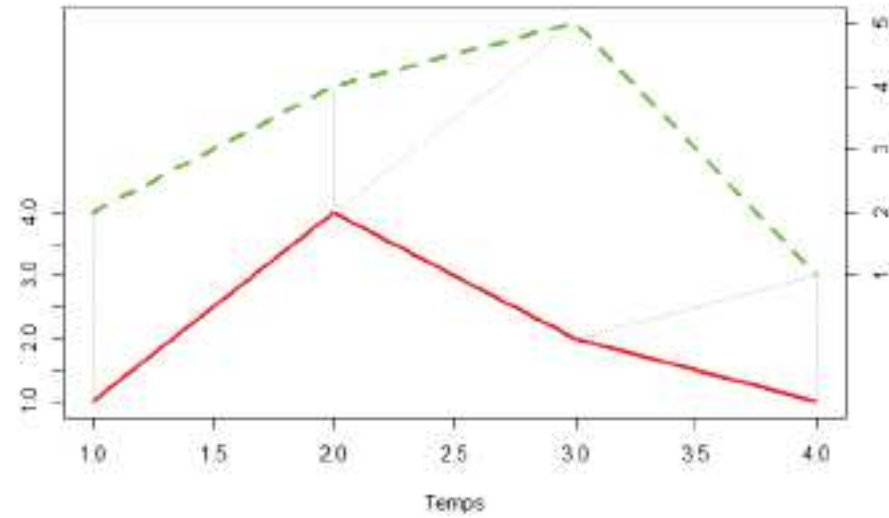
Figure: Euclidean distance (left) - DTW (right)

- The **boundarie** condition: The first (respectively last) point of both time series must be aligned.
- The **monotony** condition: during alignment there is no return to a point which has already been used.
- The **continuity** condition: when aligning all data points are considered

DTW



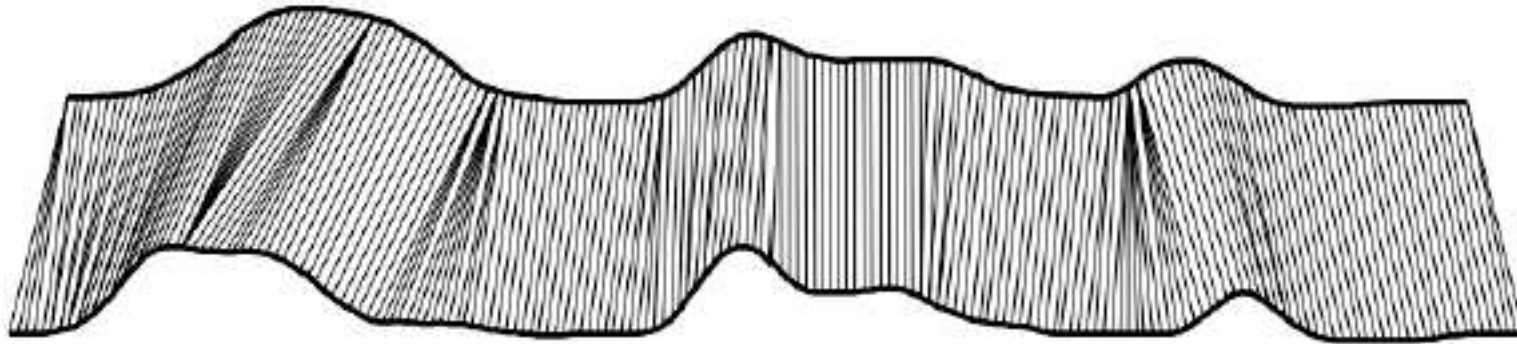
(a)



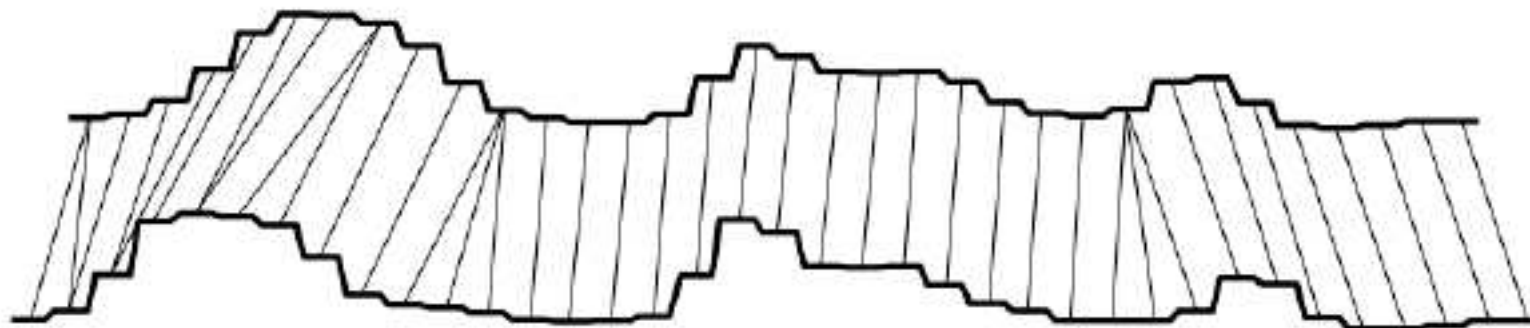
(b)

Figure: Alignment example with DTW

DTW, PDTW



(a) DTW



(b) PDTW

Figure: Keogh et Al, KDD 2000

PDTW

- An optimisation problem :
 - Finding the number of segments
- Objective function :
 - Accuracy
 - ...
- Possible solutions
 - Brute Force approach
 - IDDTW (Shu et al., SDM 2002)



IDDTW

Shu et al., SDM 2002

Considers the number of segments which are powers of two :

$$1, 2, 4, \dots, 2^k$$



Outline

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Contribution

- **FDTW**

Conclusion & prospects

- **Conclusion**
- **Future works**

FDTW

- Idea :
 - Express the number of trials as a function of the time series length, n
 - Look at the minimum number of trials with equal width, N_c
 - $N_c = \text{square root}(2n)$
- Example :
 - $n = 12$
 - $N_c = 4 \rightarrow \{3, 6, 9, 12\}$
 - Min accuracy with 6
 - Explore $[4,8]$

1, 2, [3], 4, 5, [6], 7, 8, [9], 10, 11, [12]

1, 2, 3, 4, 5, [6], 7, 8, 9, 10, 11, 12

1, 2, 3, 4, 5, [6], 7, 8, 9, 10, 11, 12

FDTW

Fact

In short, in the worst case, we test the N_c first candidates to find the best one. Then, we test $\frac{2n}{N_c}$ other candidates to find the local minimum. We finally perform $nb(N_c) = N_c + \frac{2n}{N_c}$ tests. The minimal number of tests is done when the number of candidates $N_c = \sqrt{2n}$.

FDTW

Lemma :

For a given a dataset d_i $FDTW(d_i) \leq 1NNDTW(d_i)$. The quality of the alignment of our heuristic is better than that of DTW.

Proof

$1NNDTW(d_i) = 1NNPDTW(d_i, n)$. $1NNDTW(d_i)$ is then one of the candidate considered by the heuristic $FDTW$. Since $FDTW$ returns the minimal classification error from all candidates, the classification error of $1NNDTW$ is always greater than or equal to $FDTW$. □

FDTW

Proposition :

For a given dataset d_i that has c_i classes, $c_i \in \mathbb{N}^$,
 $acc_{DTW} \geq \frac{1}{c_i} \implies \frac{1}{c_i} \times acc_{max} \leq acc_{FDTW} \leq acc_{max}$*

Algorithm 1 FDTW(training_set, test_set, n, nb_rep=log(n))

Look for a good value of the number of segments
N

using the training set

for (*i* in 0 : (nb_rep - 1)) do

tab_N ← 1 : (n - *i*)

l ← floor($n/\sqrt{2 * n}$)

tab_N_candidats ← seq(from = n, to = 1, by = -*l*)

Parallel execution of 1NNPDTW

mat_r ← 1NNPDTW(training_set, *tab_N_candidats*)

Mark candidates already used to not reuse

for (*i* in *tab_candidats*) do

tab_N[*i*] ← -1

end for

Search for the best candidate with the minimal error

min ← minimun(*mat_r*)

look for the local minimun near of the best candidate

result[[*i* + 1]] ← localMinimun(*min.N_min*, *min.error_min*, training_set, *tab_N*)

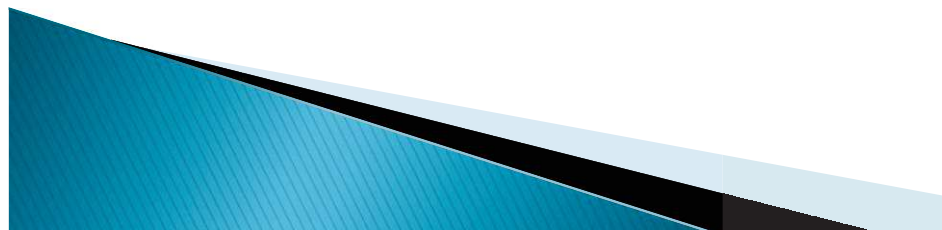
end for

The best local minimal error

m ← minimun(*result*)

return *m*

FDTW



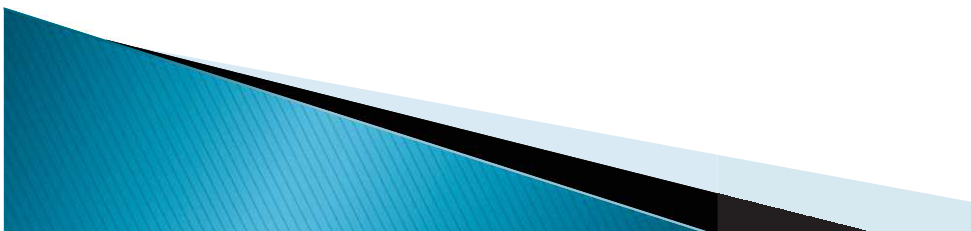
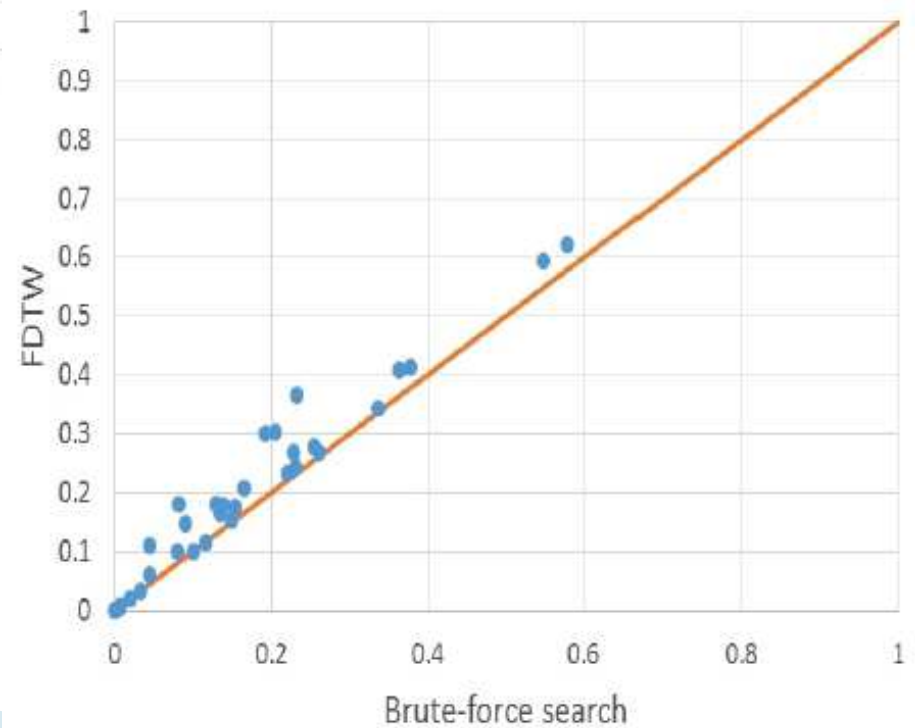
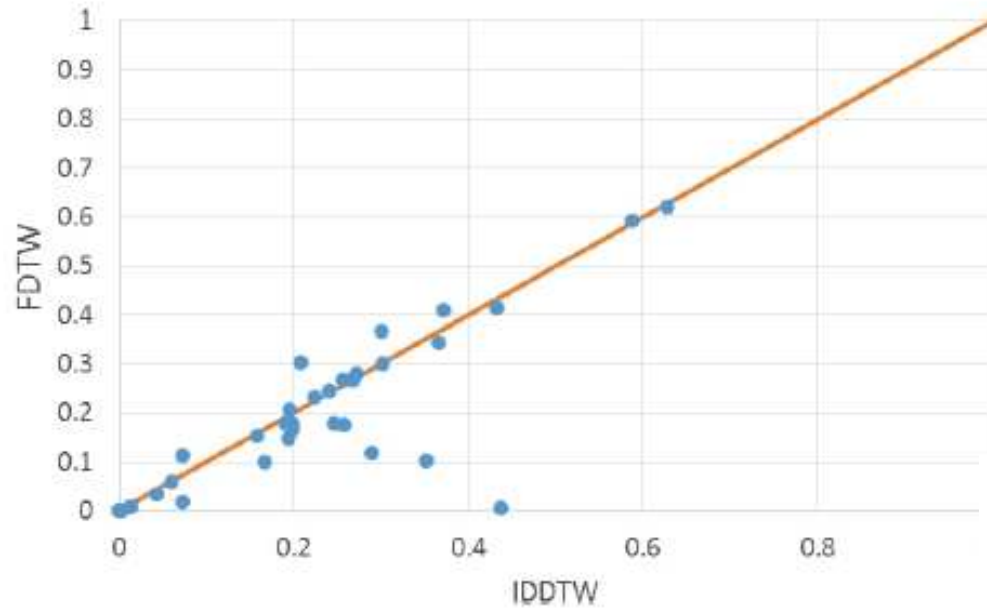
Experiments & results

Evaluation methodology

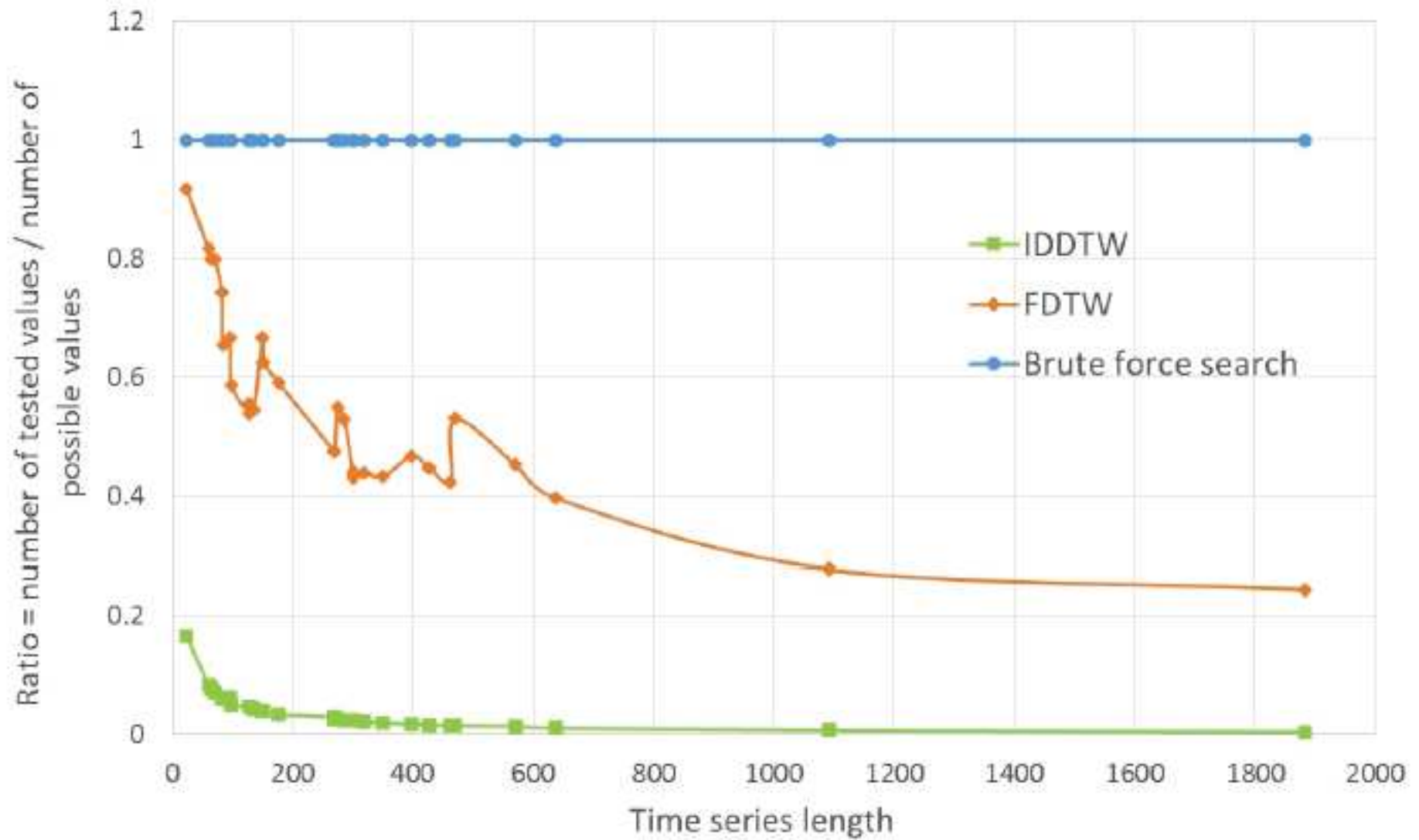
- ▶ **Interestingness**
 - Classification accuracy
 - Number of trials
- ▶ **Runtime**



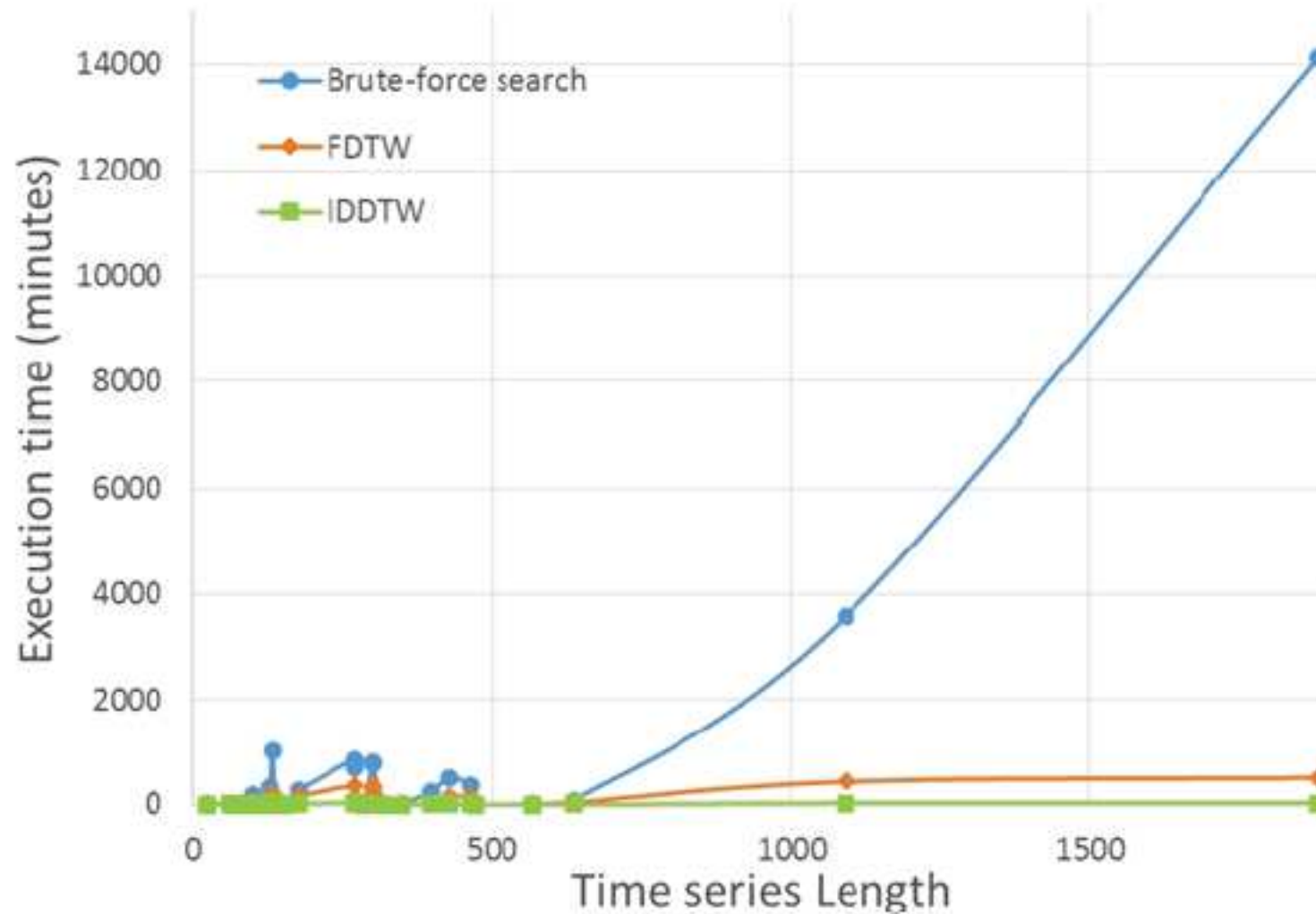
Experiments & results : Accuracy



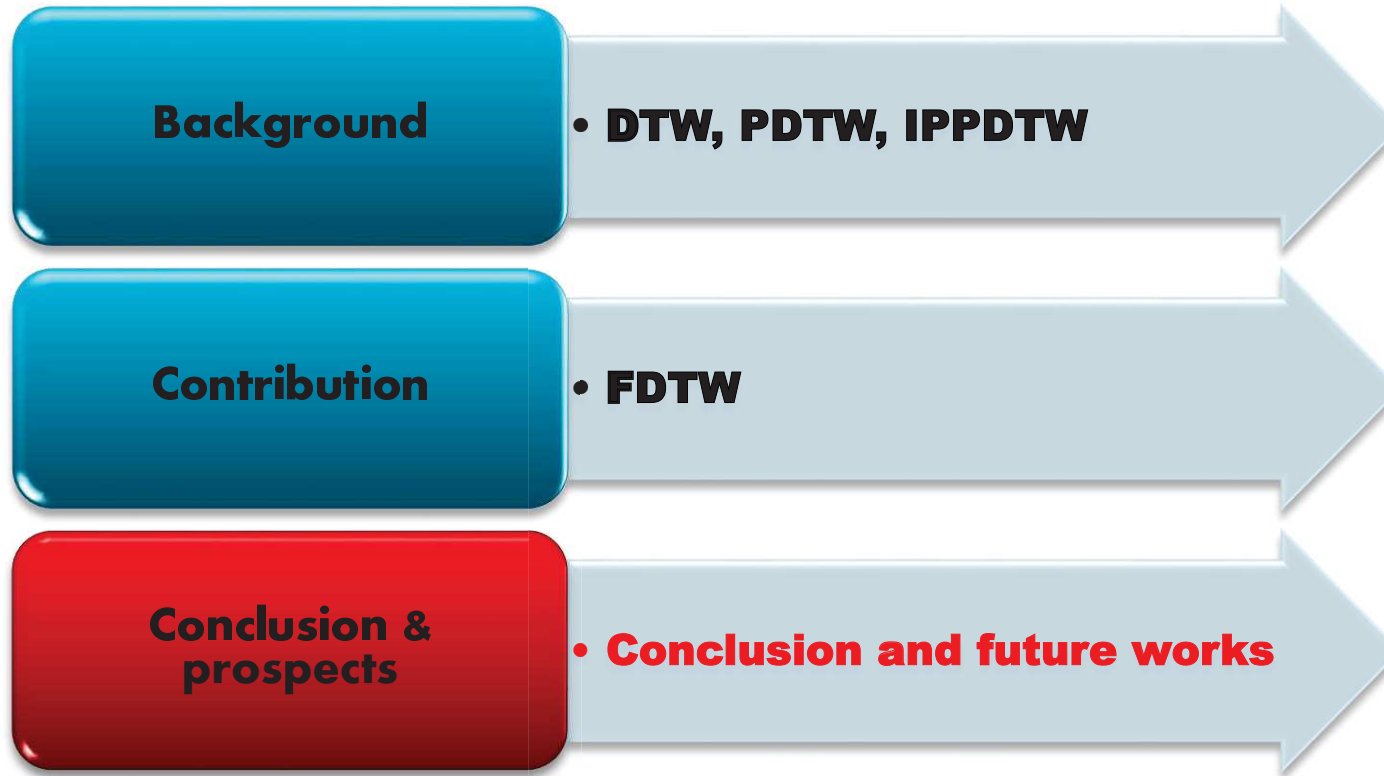
Experiments & results : #trials ratio



Experiments & results : Runtime



Outline



Conclusion

- ▶ Choice of segments length for Time Series Analysis
- ▶ The proposed approach:
 - Allows selecting a minimal number of trials
 - Searches for a local minimum
 - Can be extensible



Future works

- ▶ Extension to global minimum
- ▶ Uncertainty



Thanks

