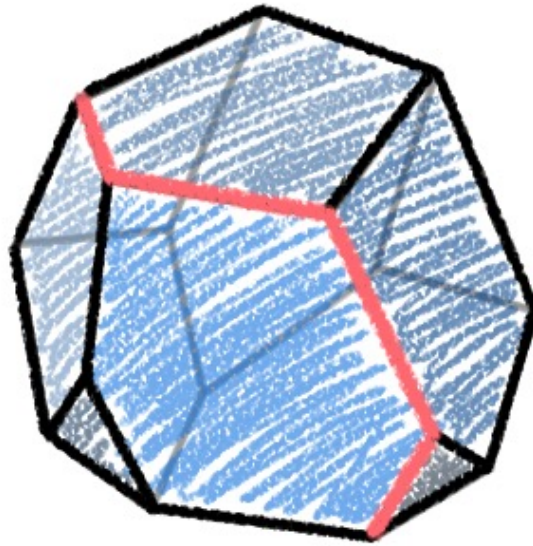


Computational, combinatorial, and geometric aspects of linear optimization



Antoine Deza, McMaster

based on joint works with:

Shmuel Onn, Technion,

Sebastian Pokutta, ZIB / TU Berlin

Lionel Pournin, Paris XIII

Linear optimization

Given an n -dimensional vector \mathbf{b} and an $n \times d$ matrix \mathbf{A} find, in any, a d -dimensional vector \mathbf{x} such that :

$$\mathbf{Ax} = \mathbf{b}$$

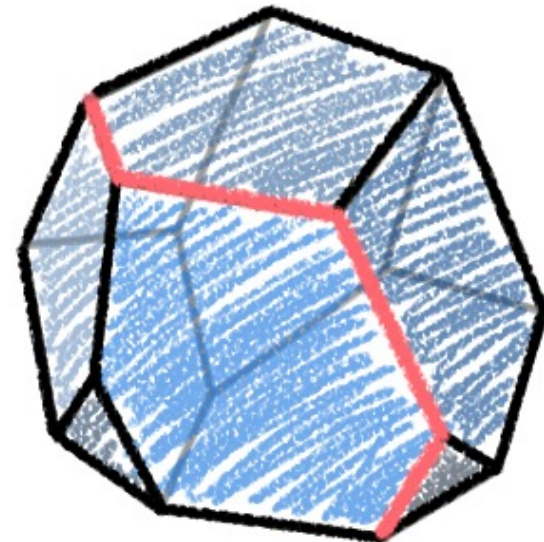
$$\mathbf{Ax} = \mathbf{b}, \mathbf{x} \geq \mathbf{0}$$

linear algebra

linear optimization

“Can linear optimization be solved in **strongly polynomial** time?”
is listed by Smale as one of the top problems for the XXI century

Strongly polynomial : algorithm **independent** from
the **input data length** and polynomial in n and d .



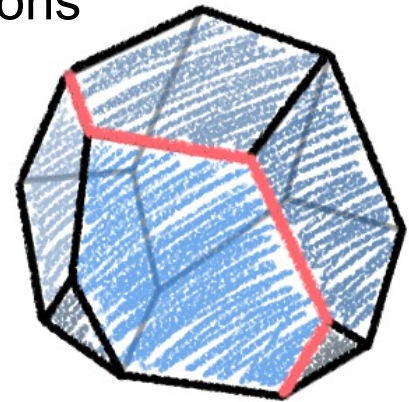
Linear optimization algorithms

simplex methods

Given an n -dimensional vector \mathbf{b} and an $n \times d$ (full row-rank) matrix \mathbf{A} and a d -dimensional cost vector \mathbf{c} , solve : $\max \{ \mathbf{c}^T \mathbf{x} : \mathbf{A} \mathbf{x} = \mathbf{b}, \mathbf{x} \geq \mathbf{0} \}$

Simplex methods (Dantzig 1947): pivot-based, combinatorial, *not proven to be polynomial*, efficient in practice

- start from a **feasible basis**
- use a **pivot rule**
- find an optimal solution after a **finite number** of iterations
- most known pivot rules are known to be **exponential** (worst case); **efficient** implementations exist



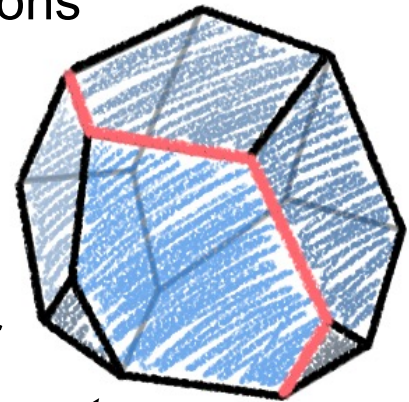
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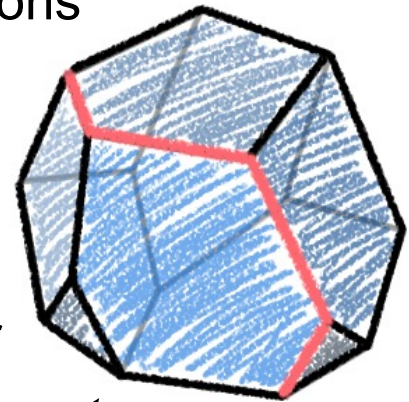
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➤ $\delta(4, 12) = \delta(5, 12) = 7$ [Bremner-Deza-Hua-Schewe 2013], ...



Linear optimization algorithms

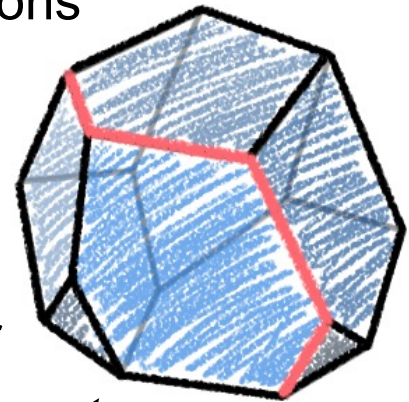
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- *random spherical* polytopes [Bonnet, Dadush, Grupel, Huiberts, Livshyts 2021], smooth analysis [Huiberts, Lee, Zhang 2024], ...



Linear optimization algorithms

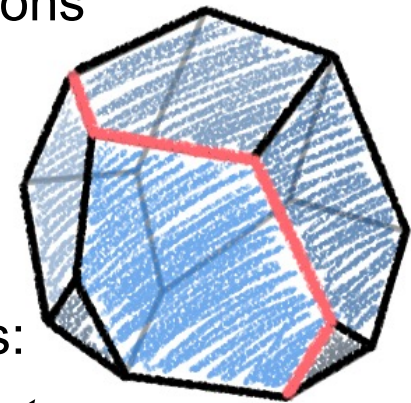
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Linear optimization algorithms

simplex methods

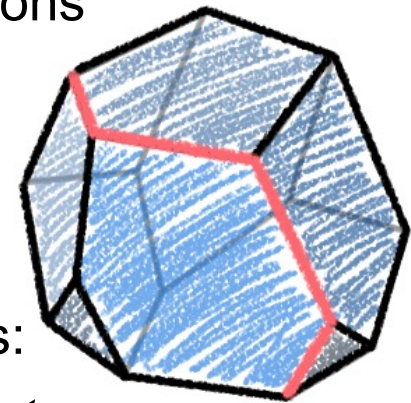
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- [Del Pia-Michini 2022] preprocessing and scaling algorithm yielding simplex paths that are short relative to $\delta(d,k)$



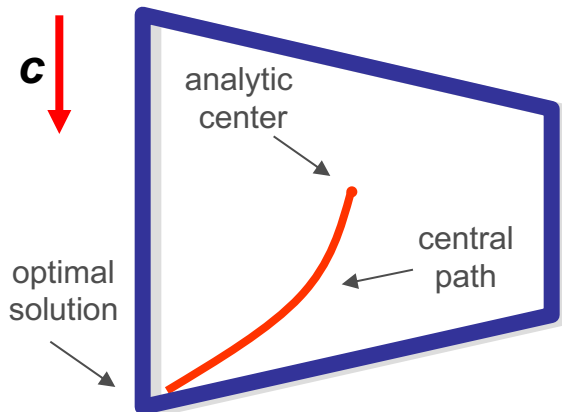
Linear optimization algorithms (central path following) interior point methods

Given an n -dimensional vector \mathbf{b} and an $n \times d$ (full row-rank) matrix \mathbf{A} and a d -dimensional cost vector \mathbf{c} , solve : $\max \{ \mathbf{c}^T \mathbf{x} : \mathbf{A} \mathbf{x} = \mathbf{b}, \mathbf{x} \geq \mathbf{0} \}$

Interior Point Methods :

path-following, *polynomial*, efficient in practice

- start from the *analytic center*
- follow the *central path*
- converge to an optimal solution in $O(\sqrt{nL})$ iterations
(L : input data length)



$$\max \quad \mathbf{c}^T \mathbf{x} - \mu \sum_i \ln(b - A\mathbf{x})_i$$

μ : central path parameter
 $\mathbf{x} \in \mathbf{P} : A\mathbf{x} \leq \mathbf{b}$

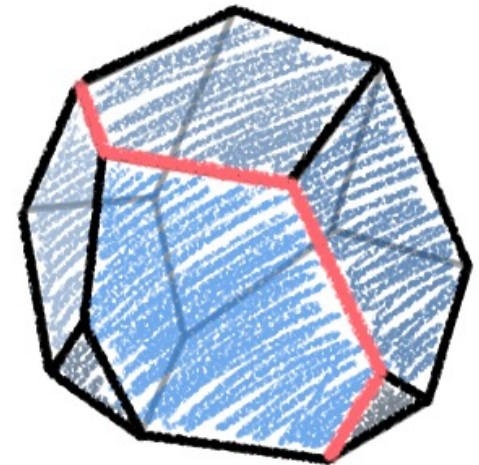
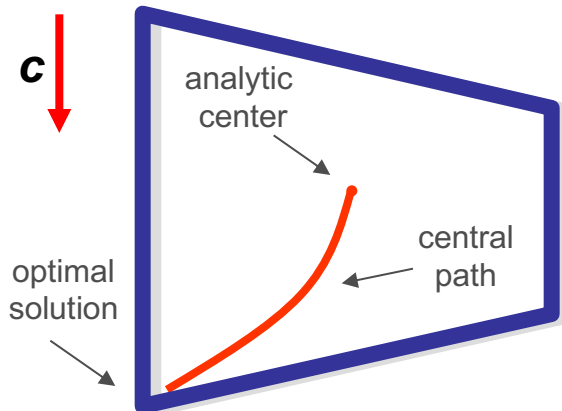
Linear optimization diameter and curvature

Diameter (of a polytope) :

lower bound for the number of iterations for *pivoting simplex methods*

Curvature (of the central path associated to a polytope) :

large curvature indicates large number of iterations for *path following interior point methods*

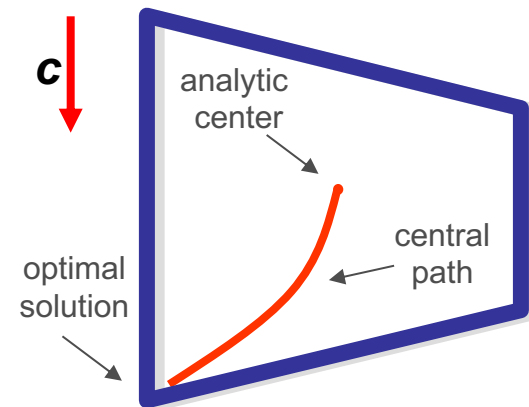


Linear optimization

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- [Dedieu-Malajovich-Shub 2005]
Average curvature of the central path is bounded by $2\pi d$
(analogue of Haimovich (Borgwardt 1987) analysis of the simplex)
- **Conjecture** [Dedieu-Malajovich 2005]
Curvature of the central path is $O(d)$
- [Deza-Terlaky-Zinchenko 2008]
Counterexample to Dedieu-Malajovich conjecture
- **Conjecture** [Deza-Terlaky-Zinchenko 2008]
Curvature of the central path is $O(n, d)$
(continuous analogue of the Hirsch conjecture)



Linear optimization

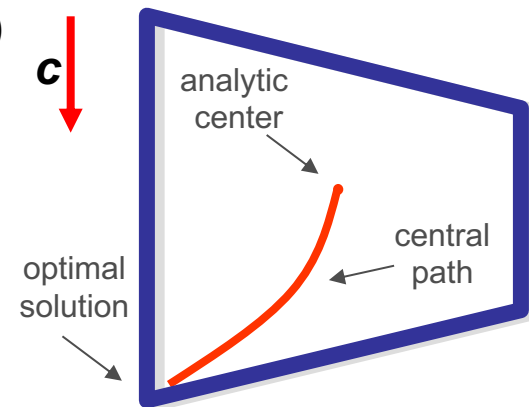
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➤ [Allamigeon, Benchimol, Gaubert, Joswig 2018]
(logarithmic barrier) **Interior point methods**
are **not strongly polynomial**
(tropical counterexample to continuous Hirsch conjecture)

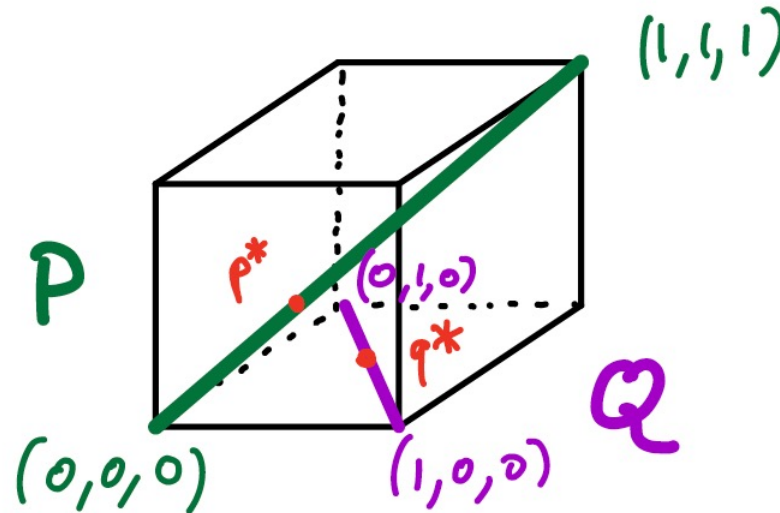
➤ [Allamigeon, Gaubert, Vandame 2022]
(self-concordant barrier) **Interior point methods**
are **not strongly polynomial**

➤ Further results: [Allamigeon-Dadush-Loho-Natura-Végh 2024] ,



Kissing Polytopes

Q. How close can two disjoint d -dimensional 0/1-polytopes be?



Motivation: this minimal distance appears in complexity bounds of algorithms such as **von Neumann's alternating projections**

Complexity of certifying that $P \cap Q = \emptyset$ is

$$O\left(\frac{1}{d(P, Q)^2}\right)$$

Alternating Linear Minimization: Revisiting von Neumann's alternating projections [Braun-Pokutta-Weismantel 2022]

Main question, motivation, related works

Related works: \mathcal{V} : vertex set of a polytope P

- **Facial distance** of P is:

$$\Phi(P) = \min\{d(F, \text{conv}(\mathcal{V} \setminus F)) : F \text{ proper face of } P\}$$

[Peña-Rodríguez 2018], [Gutman-Peña 2018], [Peña 2019]

- **Vertex-facet distance** of P is:

$$\Delta(P) = \min\{d(\text{aff}(F), \text{conv}(\mathcal{V} \setminus F)) : F \text{ facet of } P\}$$

[Beck-Shtern 2017]

- **Minimal** vertex-facet distance of all d -dimensional **0/1-simplex** S

$$\frac{1}{\sqrt{2}d \log d - 2d + o(d)} \leq \min \Delta(S) \leq \frac{1}{\sqrt{2}d \log d - 4d + o(d)}$$

[Alon-Vũ 1997]

Main results

- If P and Q are **disjoint** d -dimensional **0/1**-polytopes, then

$$\frac{1}{\sqrt{d}^{3d+2}} \leq d(P, Q)$$

- For any large enough d , there exist two **disjoint** d -dimensional **0/1**-polytopes P and Q such that

$$d(P, Q) \leq \frac{1}{\sqrt{d}\sqrt{d}}$$

Main results

- **Theorem:** For any large enough d , there exist two **disjoint** d -dimensional **0/1**-polytopes P and Q such that

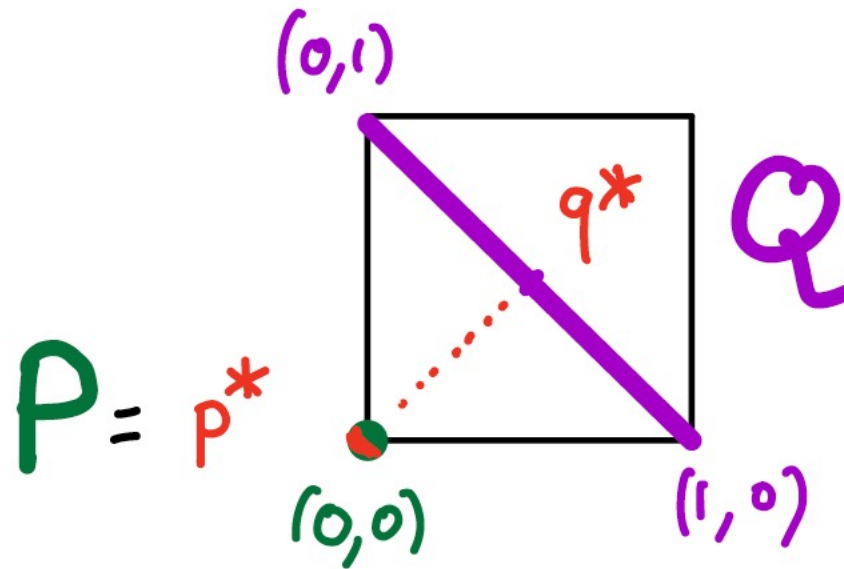
$$\frac{1}{\sqrt{d^{3d+2}}} \leq d(P, Q) \leq \frac{1}{\sqrt{d}\sqrt{d}}$$

- ⇒ Similar bounds for **lattice** (d, k) -**polytope** (that is, convex hull of points drawn from $\{0, 1, \dots, k\}^d$)
- ⇒ New bounds for the **minimal facial distance** $\Phi(P)$ over of all **lattice** (d, k) -**polytopes** P
- ⇒ Similar bounds for **rational polytopes** in terms of **binary encoding length** and dimension

How close can disjoint 0/1-polytopes be?

$\Rightarrow \varepsilon(d, 1) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$

What about dimension 2 ?

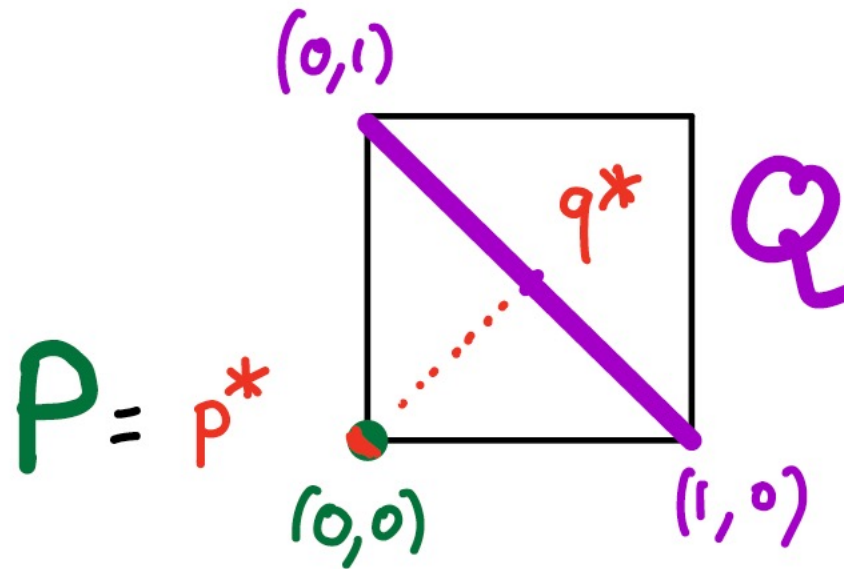


$$d(P, Q) = 0, \frac{1}{\sqrt{2}}, 1 \text{ or } \sqrt{2} \quad \Rightarrow \quad \varepsilon(2, 1) = \frac{1}{\sqrt{2}}$$

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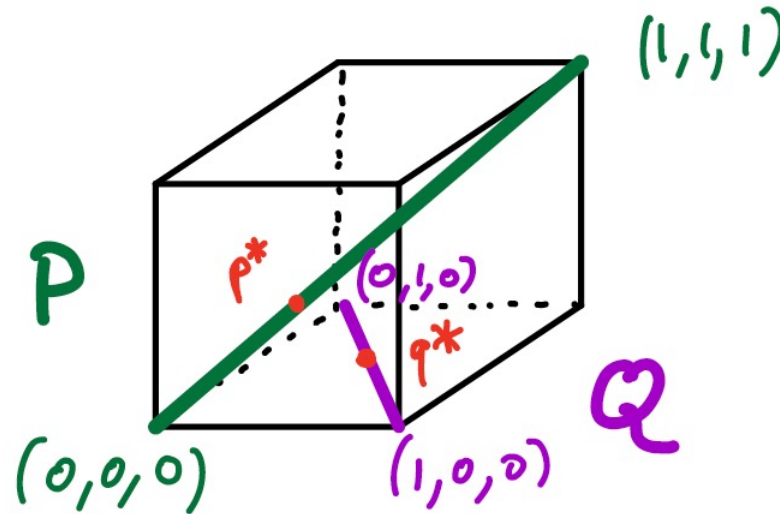
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- $\varepsilon(2, 1)$ achieved as $d(p^*, q^*)$ with q^* **not** a vertex of Q
- If P or Q is reduced to a **vertex**, $d(P, Q) \geq \frac{1}{\sqrt{d}}$ for **any** d

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What about dimension 3 ?

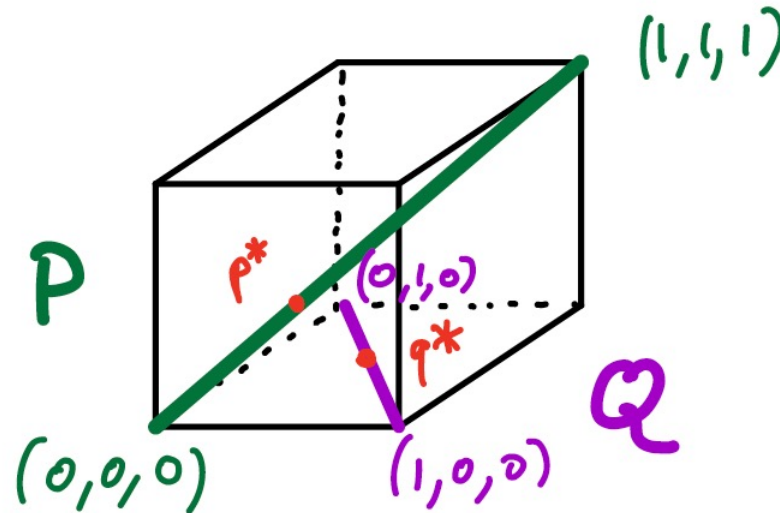


$$d(P, Q) = 0, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{3}}, \frac{2}{\sqrt{3}}, \frac{1}{\sqrt{2}}, \frac{2}{\sqrt{6}}, 1, \frac{3}{\sqrt{6}}, \sqrt{2} \text{ or } \sqrt{3} \quad \Rightarrow \quad \varepsilon(3, 1) = \frac{1}{\sqrt{6}}$$

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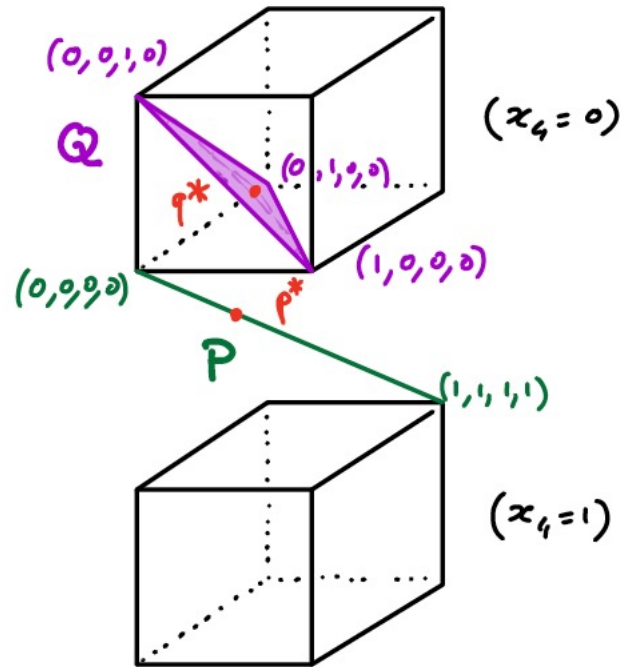
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- $\varepsilon(3, 1)$ achieved as $d(p^*, q^*)$ with both p^* and q^* **not** vertices of P, Q
- If both P and Q are **segments**, $d(P, Q) \geq \frac{1}{\sqrt{6}}$ for **any** d

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What about dimension d ?



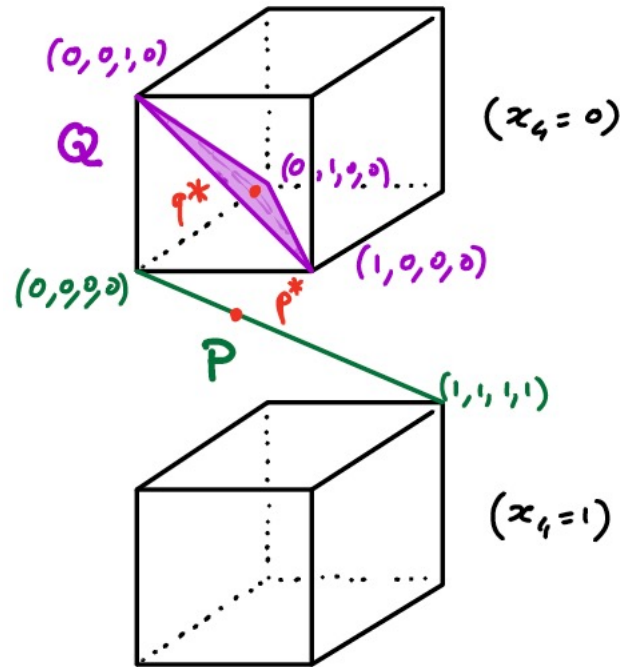
P : segment $[(0, 0, \dots, 0), (1, 1, \dots, 1)]$

Q : $(d - 2)$ -simplex with vertices $(1, 0, \dots, 0, \mathbf{0}), (0, 1, \dots, 0, \mathbf{0}), \dots, (0, 0, \dots, 1, \mathbf{0})$

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$$p^* = \frac{1}{d}(1, 1, \dots, 1), \quad q^* = \frac{1}{d-1}(1, 1, \dots, 1, 0), \quad d(p^*, q^*) = \frac{1}{\sqrt{d(d-1)}}$$

How close can disjoint 0/1-polytopes be?

$\Rightarrow \varepsilon(d, 1) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$

- **Obtaining** a non-trivial **upper bound** on $\varepsilon(d, 1)$ requires to exhibit two **disjoint polytopes** that are **very close**
- **Obtaining** a **lower bound** on $\varepsilon(d, 1)$ requires investigating the **geometric setup**

Geometric setup for rational polytopes

Remark: If P and Q are rational polytopes then $d(P, Q)^2$ is rational

Geometric setup for rational polytopes

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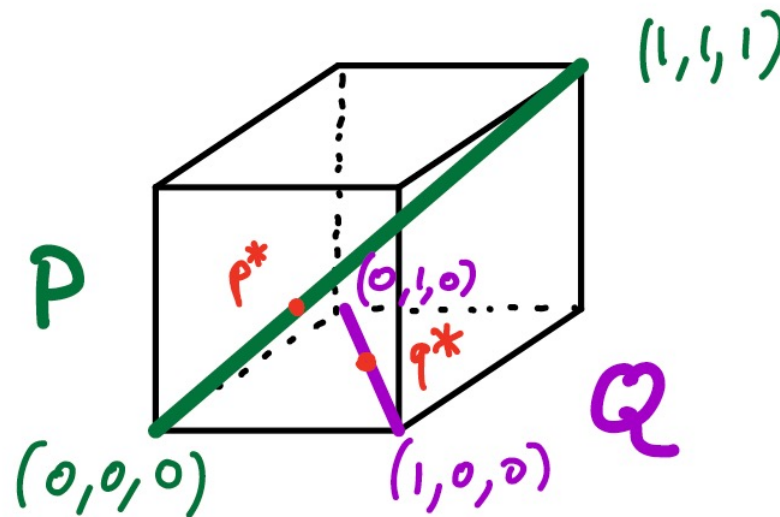
Direct consequence of stronger result on the complexity of quadratic optimization [Vavasis 1990], see also [Del Pia-Dey-Molinaro 2017]

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Direct geometric proof yields a lower bound:



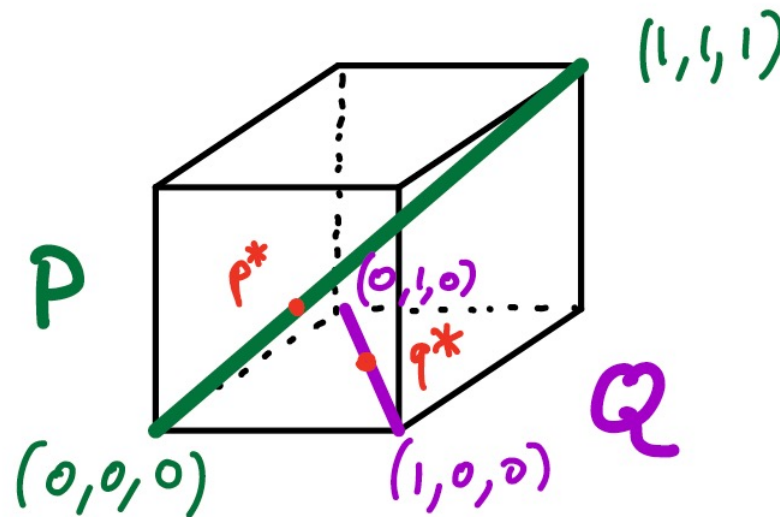
$d(P, Q)$ achieved as $d(p^*, q^*)$ with $(p^* - q^*)$ orthogonal to a unique face of P (resp. Q) containing p^* (resp. q^*) in its relative interior

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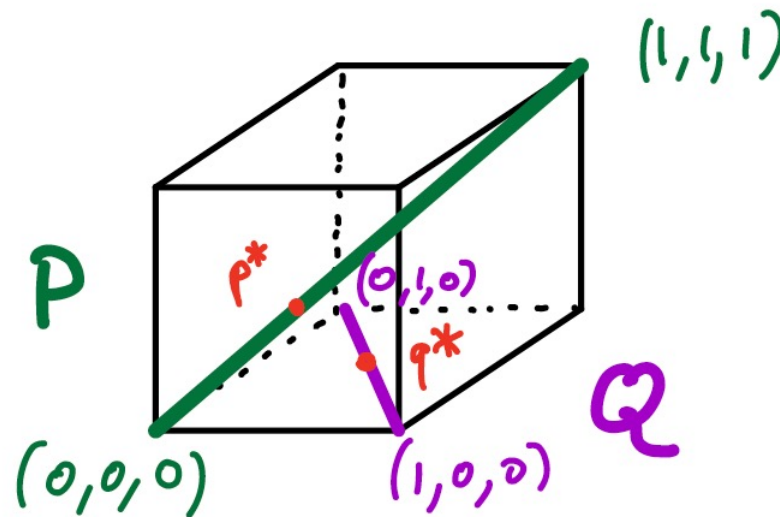
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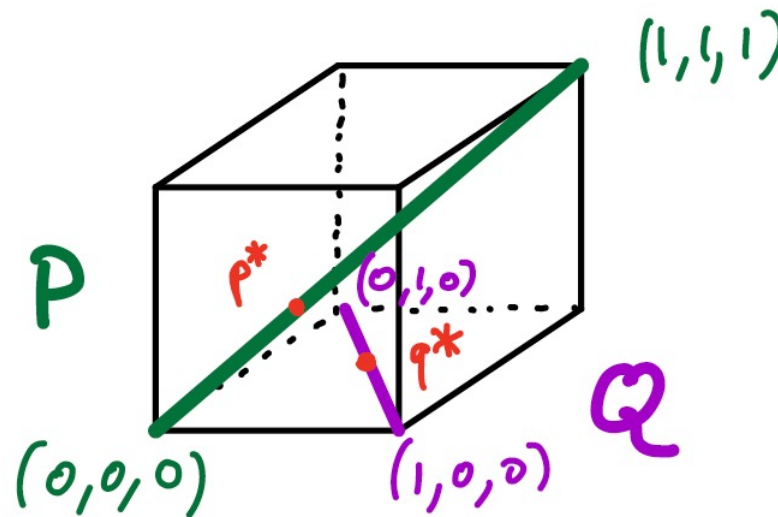
- (essentially) **Cramer's** rule yields $(p^* - q^*)$ is **rational**
- (in addition) $d(P, Q)$ can be achieved with **both** p^* and q^* **rational**

Geometric setup for rational polytopes

Remark: If P and Q are rational polytopes then $d(P, Q)^2$ is rational

Direct consequence of stronger result on the complexity of quadratic optimization [Vavasis 1990], see also [Del Pia-Dey-Molinaro 2017]

Direct geometric proof yields a lower bound:



$d(P, Q)$ achieved as $d(p^*, q^*)$ with $(p^* - q^*)$ **orthogonal** to a **unique** face of P (resp. Q) containing p^* (resp. q^*) in its **relative interior**

- (essentially) **Cramer's** rule yields $(p^* - q^*)$ is **rational**
- (essentially) **Hadamard's** inequality yields $d(p^*, q^*) \geq \frac{1}{\sqrt{d^{3d+2}}}$.

How close can disjoint 0/1-polytopes be?

$\varepsilon(d, 1) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$

$$\frac{1}{\sqrt{d^{3d+2}}} \leq \varepsilon(d, 1) \leq ?$$

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- **Obtaining** a non-trivial **upper bound** on $\varepsilon(d, \mathbf{1})$ requires to exhibit two **disjoint polytopes** that are **very close**
- **Intuition:** $d(P, Q)$ might be not too different from $d(\text{aff}(P), \text{aff}(Q))$

Example: For $i \leq d - 1$, consider two consecutive hyper-simplices:

$P = \text{convex hull of all } x \in \{0, 1\}^d \text{ such that } x_1 + x_2 + \dots + x_d = i$

$Q = \text{convex hull of all } x \in \{0, 1\}^d \text{ such that } x_1 + x_2 + \dots + x_d = i + \mathbf{1}$

$\mathbf{a} = (1, 1, \dots, 1)$ **orthogonal** to both $\text{aff}(P)$ and $\text{aff}(Q)$

$$\Rightarrow d(P, Q) = d(\text{aff}(P), \text{aff}(Q)) = \frac{1}{\sqrt{d}} = \frac{1}{\|\mathbf{a}\|}$$

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$\mathbf{a} = (1, 1, \dots, 1)$ **orthogonal** to both $\text{aff}(P)$ and $\text{aff}(Q)$

$$\Rightarrow d(P, Q) = d(\text{aff}(P), \text{aff}(Q)) = \frac{1}{\sqrt{d}} = \frac{1}{\|\mathbf{a}\|}$$

- Can we make $\|\mathbf{a}\|$ **larger** while **maintaining** $d(P, Q) = d(\text{aff}(P), \text{aff}(Q))$?

How close can disjoint 0/1-polytopes be?

$$\varepsilon(d, \mathbf{1}) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$$

Consider **much larger** $\|\mathbf{a}\|$

- $\mathbf{a} \approx (\underbrace{1, \dots, 1}_{\sqrt{d} \text{ times}}, \underbrace{-\sqrt{d}, \dots, -\sqrt{d}}_{\sqrt{d} \text{ times}}, \dots, \underbrace{(-\sqrt{d})^{\sqrt{d}}, \dots, (-\sqrt{d})^{\sqrt{d}}}_{\sqrt{d} \text{ times}})$
- $P = \text{convex hull of all } x \in \{0, 1\}^d \text{ such that } \mathbf{a} \cdot x = \mathbf{0}$
- $Q = \text{convex hull of all } x \in \{0, 1\}^d \text{ such that } \mathbf{a} \cdot x = \mathbf{1}$

Maintaining $d(P, Q) = d(\text{aff}(P), \text{aff}(Q))$:

(careful) **convex combination** of (carefully) chosen vertices in P (resp. Q) yields a point $p^* \in P$ (resp. $q^* \in Q$) such that, for d large enough

$$d(p^*, q^*) \approx \frac{1}{\|\mathbf{a}\|} \approx \frac{1}{\sqrt{d}^{\sqrt{d}}}$$

How close can disjoint lattice polytopes be?

$\varepsilon(d, 1) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$

$$\frac{1}{\sqrt{d}^{3d+2}} \leq \varepsilon(d, 1) \leq \frac{1}{\sqrt{d}^{\sqrt{d}}}$$

$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$

$$\frac{1}{k^{2d-1}\sqrt{d}^{3d+2}} \leq \varepsilon(d, k) \leq \frac{1}{(k\sqrt{d})^{\sqrt{d}}}$$

How close can disjoint lattice polytopes be?

$\varepsilon(d, 1) = \min\{d(P, Q) : P, Q \text{ disjoint } d\text{-dimensional } 0/1\text{-polytopes}\}$

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$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$

$$\frac{1}{k^{2d-1}\sqrt{d}^{3d+2}} \leq \varepsilon(d, k) \leq \frac{1}{(k\sqrt{d})^{\sqrt{d}}}$$

Q. How to **compute** the minimal distance between disjoint lattice polytopes for small dimension d and small range k ?

How close can disjoint lattice polytopes be?

$$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$$

Exploiting the **symmetries** of the cube, proving that one can assume that P is a simplex such that $1 \leq \dim(P) \leq \lfloor \frac{d}{2} \rfloor$, and Q is a simplex such that $\dim(Q) = d + 1 - \dim(P)$, significantly reduce the huge search space and allow for the **computation** of $\varepsilon(d, k)$ for small (d, k) :

(d, k)	1	2	3	4	5	6
$\frac{1}{\varepsilon(2, k)}$	$\sqrt{2}$	$\sqrt{5}$	$\sqrt{13}$	$\sqrt{25}$	$\sqrt{41}$	$\sqrt{61}$
$\frac{1}{\varepsilon(3, k)}$	$\sqrt{6}$	$\sqrt{50}$	$\sqrt{299}$			
$\frac{1}{\varepsilon(4, k)}$	$\sqrt{18}$					
$\frac{1}{\varepsilon(5, k)}$	$\sqrt{58}$					

How close can disjoint lattice polytopes be?

$$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$$

[Deza-Liu-Pournin 2024]

- $\varepsilon(2, k) = \frac{1}{\sqrt{(k-1)^2 + k^2}}$ for $k \geq 2$
- $\varepsilon(3, k) = \frac{1}{\sqrt{2(2k^2 - 4k + 5)(2k^2 - 2k + 1)}}$ for $k \geq 4$

Determination of $\varepsilon(3, k)$ amounts to minimize

$$\frac{|\mathbf{f}(x)|}{\sqrt{\mathbf{g}(x)}}$$

$$\mathbf{f}(x) = x_1(x_6x_8 - x_5x_9) + x_2(x_4x_9 - x_6x_7) + x_3(x_5x_7 - x_4x_8)$$

$$\mathbf{g}(x) = (x_1x_5 - x_2x_4)^2 + (x_1x_6 - x_3x_4)^2 + (x_2x_6 - x_3x_5)^2$$

such that $\mathbf{f}(x) \neq 0$, $\mathbf{g}(x) \neq 0$, $-k \leq x_i \leq k$, x_i integer for $i = 1, 2, \dots, 9$

How close can disjoint lattice polytopes be?

$$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$$

(d, k)	1	2	3	4	...	k
$\frac{1}{\varepsilon(2, k)}$	$\sqrt{2}$	$\sqrt{5}$	$\sqrt{13}$	$\sqrt{25}$...	$\sqrt{(k-1)^2 + k^2}$
$\frac{1}{\varepsilon(3, k)}$	$\sqrt{6}$	$\sqrt{50}$	$\sqrt{299}$	$\sqrt{1050}$...	$\sqrt{2(2k^2 - 4k + 5)(2k^2 - 2k + 1)}$
$\frac{1}{\varepsilon(4, k)}$	$\sqrt{18}$					
$\frac{1}{\varepsilon(5, k)}$	$\sqrt{58}$					

How close can disjoint lattice polytopes be?

$$\varepsilon(d, k) = \min\{d(P, Q) : P, Q \text{ disjoint lattice } (d, k)\text{-polytopes}\}$$

(d, k)	1	2	3	4	...	k
$\frac{1}{\varepsilon(2, k)}$	$\sqrt{2}$	$\sqrt{5}$	$\sqrt{13}$	$\sqrt{25}$...	$\sqrt{(k-1)^2 + k^2}$
$\frac{1}{\varepsilon(3, k)}$	$\sqrt{6}$	$\sqrt{50}$	$\sqrt{299}$	$\sqrt{1050}$...	$\sqrt{2(2k^2 - 4k + 5)(2k^2 - 2k + 1)}$
$\frac{1}{\varepsilon(4, k)}$	$\sqrt{18}$					
$\frac{1}{\varepsilon(5, k)}$	$\sqrt{58}$					

Thanks